

Hilbert domains that admit a quasi-isometric embedding into Euclidean space

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Abstract. We prove that a Hilbert domain which admits a quasi-isometric embedding into a finite-dimensional normed vector space is actually a convex polytope.

Key words. Primary: global Finsler geometry, Secondary: convexity.

1 Introduction

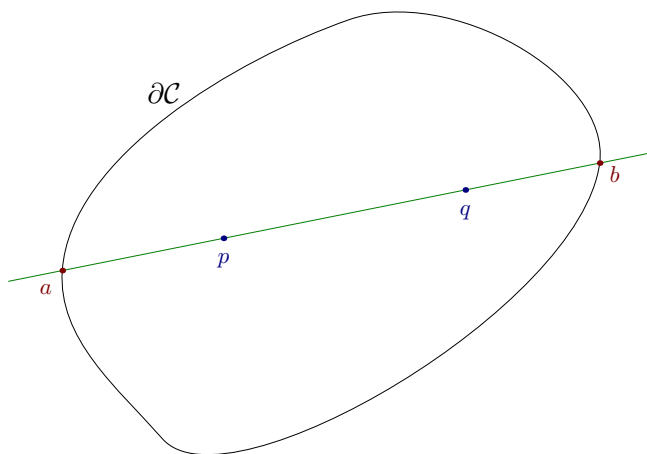
A *Hilbert domain* in \mathbb{R}^m is a metric space $(\mathcal{C}, d_{\mathcal{C}})$, where \mathcal{C} is an *open bounded convex* set in \mathbb{R}^m and $d_{\mathcal{C}}$ is the distance function on \mathcal{C} — called the *Hilbert metric* — defined as follows. Given two distinct points p and q in \mathcal{C} , let a and b be the intersection points of the straight line defined by p and q with $\partial\mathcal{C}$ so that $p = (1 - s)a + sb$ and $q = (1 - t)a + tb$ with $0 < s < t < 1$. Then

$$d_{\mathcal{C}}(p, q) := \frac{1}{2} \ln [a, p, q, b], \quad \text{where}$$
$$[a, p, q, b] := \frac{1 - s}{s} \times \frac{t}{1 - t} > 1$$

is the cross ratio of the 4-tuple of ordered collinear points (a, p, q, b) . We complete the definition by setting $d_{\mathcal{C}}(p, p) := 0$.

The metric space $(\mathcal{C}, d_{\mathcal{C}})$ thus obtained is a complete non-compact geodesic metric space whose topology is the one induced by the canonical topology of \mathbb{R}^m and in which the affine open segments joining two points of the boundary $\partial\mathcal{C}$ are geodesic lines. For further information about Hilbert geometry, we refer to [4, 5, 9, 11] and the excellent introduction [15] by Socié-Méthou.

The two fundamental examples of Hilbert domains $(\mathcal{C}, d_{\mathcal{C}})$ in \mathbb{R}^m correspond to the case when \mathcal{C} is an ellipsoid, which gives the Klein model of m -dimensional hyperbolic



geometry (see for example [15, first chapter]), and the case when the closure \bar{C} is a m -simplex for which there exists a norm $\|\cdot\|_C$ on \mathbb{R}^m such that (C, d_C) is isometric to the normed vector space $(\mathbb{R}^m, \|\cdot\|_C)$ (see [8, pages 110–113] or [14, pages 22–23]).

Much has been done to study the similarities between Hilbert and hyperbolic geometries (see for example [7], [16] or [1]), but little literature deals with the question of knowing to what extent a Hilbert geometry is close to that of a normed vector space in terms of *quasi-isometric embeddings* which are defined as follows (see Definition 8.14 in [3], page 138):

Definition. Given real numbers $A \geq 1$ and $B \geq 0$, a metric space (S, d) , and a normed vector space $(V, \|\cdot\|)$, a map $f : S \rightarrow V$ is said to be a (A, B) -*quasi-isometric embedding* if

$$\frac{1}{A}d(p, q) - B \leq \|f(p) - f(q)\| \leq Ad(p, q) + B$$

for all $p, q \in S$.

Definition. With this definition, a map $f : S \rightarrow V$ is called a *Lipschitz equivalence* if it is a bijection that is a $(A, 0)$ -quasi-isometric embedding for some $A \geq 1$.

Let us then mention three results which are relevant for our present work.

Theorem 1.1 ([10], Theorem 2). *A Hilbert domain (C, d_C) in \mathbb{R}^m is isometric to some normed vector space if and only if C is the interior of a m -simplex.*

Theorem 1.2 ([6], Theorem 3.1). *If C is an open convex polygonal set in \mathbb{R}^2 , then (C, d_C) is Lipschitz equivalent to the Euclidean plane.*

Theorem 1.3 ([2], Theorem 1.1. See also [17]). *If C is an open set in \mathbb{R}^m whose closure \bar{C} is a convex polytope, then (C, d_C) is Lipschitz equivalent to Euclidean m -space.*

Recall that a convex *polytope* in \mathbb{R}^m (called a convex *polygon* when $m := 2$) is the convex hull of a finite set of points whose affine span is the whole space \mathbb{R}^m . In the light of these facts, it is natural to ask whether the converse of Theorem 1.3 — which generalizes Theorem 1.2 in higher dimensions — holds. In other words, if a Hilbert domain (C, d_C) in \mathbb{R}^m admits a quasi-isometric embedding into a normed vector space, what can be said about C ? The answer to that question is given by the following result which asserts that the converse of Theorem 1.3 is actually true:

Theorem 1.4. *If a Hilbert domain (C, d_C) in \mathbb{R}^m admits a quasi-isometric embedding into a finite-dimensional normed vector space $(V, \|\cdot\|)$, then C is the interior of a convex polytope.*

2 Proof of Theorem 1.4

The proof of Theorem 1.4 is based on an idea developed by Foertsch and Karlsson in their paper [10]. For this purpose, let us first introduce a definition:

Definition. Given a convex set C in \mathbb{R}^m and $x, y \in \partial C$, we will say that the points x and y are *neighbors* if the line segment $[x, y]$ between them is contained in the boundary ∂C .

To establish Theorem 1.4, we need the following fact due to Karlsson and Noskov:

Theorem 2.1 ([12], Theorem 5.2). *Let (C, d_C) be a Hilbert domain in \mathbb{R}^m and $x, y \in \partial C$ such that x and y are not neighbors. Then, fixing any point $p_0 \in C$, there exists a constant $K(p_0, x, y) > 0$ such that for any sequences $(x_n)_{n \in \mathbb{N}}$ and $(y_n)_{n \in \mathbb{N}}$ in C that converge respectively to x and y in \mathbb{R}^m one has*

$$d_C(x_n, y_n) \geq d_C(x_n, p_0) + d_C(y_n, p_0) - K(p_0, x, y)$$

for sufficiently large n .

Now, here is the key result which gives the proof of Theorem 1.4:

Proposition 2.1. *Let (C, d_C) be a Hilbert domain in \mathbb{R}^m which admits a (A, B) -quasi-isometric embedding into a finite-dimensional normed vector space $(V, \|\cdot\|)$ for some real constants $A \geq 1$ and $B \geq 0$. Then, if $N = N(A, \|\cdot\|)$ denotes the maximum number of points in the ball $\{v \in V \mid \|v\| \leq 2A\}$ whose pairwise distances with respect to $\|\cdot\|$ are greater than or equal to $1/(2A)$, and if $X \subseteq \partial C$ consists of pairwise non-neighboring points, we have $\text{card}(X) \leq N$.*

Definition. The finiteness of the dimension of V is essential here since it yields the compactness of the ball $\{v \in V \mid \|v\| \leq 2A\}$, insuring that N is well defined (indeed, if there were an infinite number of points in this ball whose pairwise distances with respect to $\|\cdot\|$ are greater than or equal to $1/(2A)$, then these points would have an accumulation point

in this ball, which is impossible). On the other hand, it is worth remembering that *any* metric space (S, d) can be *isometrically* embedded into the *infinite*-dimensional space of bounded real functions on S endowed with the uniform norm.

Proof of Proposition 2.1. Let $f : \mathcal{C} \rightarrow V$ such that

$$\frac{1}{A}d_{\mathcal{C}}(p, q) - B \leq \|f(p) - f(q)\| \leq Ad_{\mathcal{C}}(p, q) + B \tag{2.1}$$

for all $p, q \in \mathcal{C}$. First of all, up to translations, we may assume that $0 \in \mathcal{C}$ and $f(0) = 0$.

Then suppose that there exists a subset X of the boundary $\partial\mathcal{C}$ such that $[x, y] \not\subseteq \partial\mathcal{C}$ for all $x, y \in X$ with $x \neq y$ and $\text{card}(X) \geq N + 1$. So, pick $N + 1$ distinct points x_1, \dots, x_{N+1} in X , and for each $k \in \{1, \dots, N + 1\}$, let $\gamma_k : [0, +\infty) \rightarrow \mathcal{C}$ be a geodesic of $(\mathcal{C}, d_{\mathcal{C}})$ that satisfies $\gamma_k(0) = 0$, $\lim_{t \rightarrow +\infty} \gamma_k(t) = x_k$ in \mathbb{R}^m and $d_{\mathcal{C}}(0, \gamma_k(t)) = t$ for all $t \geq 0$.

This implies that for all integer $n \geq 1$ and every $k \in \{1, \dots, N + 1\}$, we have

$$\left\| \frac{f(\gamma_k(n))}{n} \right\| \leq A + \frac{B}{n} \tag{2.2}$$

from the second inequality in Equation 2.1 with $p := \gamma_k(n)$ and $q := 0$. On the other hand, Theorem 2.1 yields the existence of some integer $n_0 \geq 1$ such that

$$d_{\mathcal{C}}(\gamma_i(n), \gamma_j(n)) \geq 2n - K(0, x_i, x_j)$$

for all integer $n \geq n_0$ and every $i, j \in \{1, \dots, N + 1\}$ with $i \neq j$, and hence

$$\left\| \frac{f(\gamma_i(n))}{n} - \frac{f(\gamma_j(n))}{n} \right\| \geq \frac{2}{A} - \frac{1}{n} \left(\frac{K(0, x_i, x_j)}{A} + B \right) \tag{2.3}$$

from the first inequality in Equation 2.1 with $p := \gamma_i(n)$ and $q := \gamma_j(n)$.

Now, fixing an integer $n \geq n_0 + AB + \max\{K(0, x_i, x_j) \mid i, j \in \{1, \dots, N + 1\}\}$, we get

$$\left\| \frac{f(\gamma_k(n))}{n} \right\| \leq 2A$$

for all $k \in \{1, \dots, N + 1\}$ by Equation 2.2 together with

$$\left\| \frac{f(\gamma_i(n))}{n} - \frac{f(\gamma_j(n))}{n} \right\| \geq \frac{1}{2A}$$

for all $i, j \in \{1, \dots, N + 1\}$ with $i \neq j$ by Equation 2.3. But this contradicts the definition of $N = N(A, \|\cdot\|)$. □

Owing to Proposition 2.1, Theorem 1.4 is then a straightforward consequence of the following:

Proposition 2.2. *Let \mathcal{C} be an open bounded convex set in \mathbb{R}^m . Then $\overline{\mathcal{C}}$ is a convex polytope if and only if there exists an integer $N \geq 1$ such that every set $X \subseteq \partial\mathcal{C}$ made up of pairwise non-neighboring points satisfies $\text{card}(X) \leq N$.*

The proof of Proposition 2.2 will use two useful results.

Lemma 2.1. *In a convex set \mathcal{C} in \mathbb{R}^2 , any extreme point (hence in $\partial\mathcal{C}$) has at most two other extreme points as neighbors.*

Theorem 2.2 ([13], Theorem 4.7). *Let P be a convex set in \mathbb{R}^m and $p \in \overset{\circ}{P}$. Then P is a convex polyhedron if and only if all its plane sections containing p are convex polyhedra.*

Here, as usual, a convex *polyhedron* in \mathbb{R}^m is the intersection of a finite number of closed half-spaces.

Proof of Lemma 2.1. Suppose there exists an extreme point p_0 of \mathcal{C} that has three other extreme points m , p and q in \mathcal{C} as neighbors. Up to translations, we may assume that $p_0 = 0$. Since $[0, p]$ and $[0, q]$ are contained in the boundary $\partial\mathcal{C}$, the straight lines $(0p)$ and $(0q)$ are supporting lines to \mathcal{C} , and hence \mathcal{C} lies in the half-cone $\{\lambda p + \mu q \mid \lambda \geq 0 \text{ and } \mu \geq 0\}$.

In particular, we can write $m = \lambda_0 p + \mu_0 q$ for some $\lambda_0 > 0$ and $\mu_0 > 0$ (being extreme in \mathcal{C} , the points m and p can neither satisfy $m \in [0, p]$, nor $p \in [0, m]$; therefore λ_0 cannot vanish, and the same holds for μ_0).

Now the open convex hull $\{\lambda p + \mu q \mid \lambda > 0, \mu > 0 \text{ and } \lambda + \mu = 1\}$ of the points $0, p, q \in \mathcal{C}$ is contained in $\overset{\circ}{\mathcal{C}}$, which yields $m/(\lambda_0 + \mu_0) \in \overset{\circ}{\mathcal{C}}$. Therefore, since $m/(\lambda_0 + \mu_0) \in [0, m]$, we get $[0, m] \not\subseteq \partial\mathcal{C}$, contradicting the fact that 0 and m are neighbors. \square

Proof of Proposition 2.2. If \mathcal{C} is a convex polytope, then any two points in $\partial\mathcal{C}$ that are not neighbors belong to two different 2-dimensional faces of \mathcal{C} . Thus, every set $X \subseteq \partial\mathcal{C}$ consisting of pairwise non-neighboring points satisfies $\text{card}(X) \leq N$, where N denotes the number of 2-dimensional faces of \mathcal{C} . On the other hand, if \mathcal{C} is not a convex polytope, then Theorem 2.2 implies that there exists a plane section of \mathcal{C} which is not a convex polygon. So, we may assume that $m = 2$.

Since any compact convex set in a finite-dimensional real vector space is the convex hull of its extreme points (Minkowski's Theorem), \mathcal{C} has infinitely many extreme points. Then, using Lemma 2.1, one can construct by induction a sequence $(x_n)_{n \in \mathbb{N}}$ of extreme points in \mathcal{C} such that for all $n \in \mathbb{N}$ the point x_{n+1} has no neighbors in $\{x_0, \dots, x_n\}$, and hence the set $X := \{x_n \mid n \in \mathbb{N}\} \subseteq \partial\mathcal{C}$ is infinite and is made up of pairwise non-neighboring points. This proves Proposition 2.2. \square

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